

# TSDT14 Signal Theory

## Solutions to the exam 2018-10-24

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**1**

These subtasks have to be treated correctly as partial fulfillment to pass the exam.

- a. An ensemble average is the expectation of a function of samples of a stochastic process. Examples are the expectation of a process, its variance or its ACF.
- b. We have for the pulse-amplitude-modulated signal

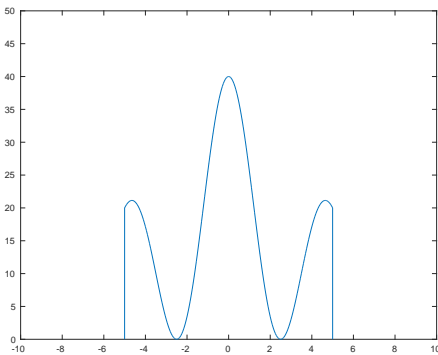
$$R_Y(f) = \frac{1}{T} |P(f)|^2 R_X[fT]$$

Plugging in everything given in the task, we get

$$R_Y(f) = \begin{cases} 20 \cos^2(2\pi f/10) (1 + \cos(2\pi f/20)), & |f| < 5 \text{ Hz}, \\ 0, & \text{elsewhere} \end{cases}$$

$$= \begin{cases} 40 \cos^2(2\pi f/10) \cos^2(2\pi f/40), & |f| < 5 \text{ Hz}, \\ 0, & \text{elsewhere} \end{cases}$$

Graphically:



- c. We have a stochastic variable that is uniformly distributed on the interval  $[-A, A]$ . It is uniformly quantized with  $N = 256$  quantization steps and saturation levels  $\pm A$ . For the quantization step  $\Delta$ , we have

$$N\Delta = 2A.$$

From that we find the quantization step

$$\Delta = \frac{2A}{N}.$$

The quantization error  $Q$  has according to the Tables and Formulas booklet on page 16 the power

$$P_Q = \frac{\Delta^2}{12} = \frac{A^2}{3N^2},$$

and that is our distortion.

**2**

The mean of the input is  $m_X = 0$ . The filter is LTI. Therefore, the mean of the output is  $m_Y = m_X \cdot H(0) = 0$ . The ACF of the input is

$$r_X(\tau) = 10^3 \cdot \text{sinc}(10^3\tau).$$

Tables and Formulas, p. 18, gives us the PSD

$$R_X(f) = \text{rect}\left(\frac{f}{10^3}\right) = \begin{cases} 1, & |f| < 500, \\ 0, & \text{elsewhere.} \end{cases}$$

The given frequency response of the filter is

$$H(f) = \begin{cases} 1 - \frac{|f|}{10^3}, & |f| < 10^3, \\ 0, & \text{elsewhere.} \end{cases}$$

Since the system is LTI, we have the output PSD

$$R_Y(f) = |H(f)|^2 R_X(f) = \begin{cases} \left(1 - \frac{|f|}{10^3}\right)^2, & |f| < 500, \\ 0, & \text{elsewhere.} \end{cases}$$

The mean is zero, which gives us

$$\sigma_Y^2 = E\{Y^2(t)\} = r_X(0) = \int_{-\infty}^{\infty} R_Y(f) df$$

$$= \int_{-500}^{500} \left(1 - \frac{|f|}{10^3}\right)^2 df = 2 \int_{-500}^0 \left(1 + \frac{f}{10^3}\right)^2 df.$$

The variable substitution  $g = f + 10^3$  rewrites the expression above as

$$\sigma_Y^2 = 2 \int_{500}^{1000} \left( \frac{g}{10^3} \right)^2 df = \frac{1750}{3}$$

Finally, we calculate the probability

$$\Pr\{|Y| > 5\} = 2 \cdot Q\left(\frac{5}{\sigma_Y}\right) \approx 2 \cdot Q(0.21) \approx 0.83$$

### 3

We have two WSS signals  $X(t)$  and  $Y(t)$ , both with mean zero. We also have a random phase  $\Psi$  that is uniformly distributed on  $[0, 2\pi)$  and independent of both  $X(t)$  and  $Y(t)$ . We are interested in the signal

$$Z(t) = X(t) \cos(2\pi f_c t + \Psi) + Y(t) \sin(2\pi f_c t + \Psi),$$

where  $f_c$  is a carrier frequency.

- a. We are to prove that  $Z(t)$  can be WSS even if  $X(t)$  and  $Y(t)$  are dependent, and determine what demands have to be fulfilled then.

First, we check the mean:

$$\begin{aligned} m_Z &= \mathbb{E}\{X(t) \cos(2\pi f_c t + \Psi) + Y(t) \sin(2\pi f_c t + \Psi)\} \\ &= m_X \mathbb{E}\{\cos(2\pi f_c t + \Psi)\} + m_Y \mathbb{E}\{\sin(2\pi f_c t + \Psi)\} \\ &= 0, \end{aligned}$$

which is constant. Here, we have used the independence of  $\Psi$  and each of the two signals  $X(t)$  and  $Y(t)$  in the second equality.

Next, we check the ACF:

$$\begin{aligned} r_Z(t + \tau, t) &= \mathbb{E}\left\{ \left( X(t + \tau) \cos(2\pi f_c(t + \tau) + \Psi) + Y(t + \tau) \sin(2\pi f_c(t + \tau) + \Psi) \right) \right. \\ &\quad \left. \cdot \left( X(t) \cos(2\pi f_c t + \Psi) + Y(t) \sin(2\pi f_c t + \Psi) \right) \right\} \\ &= \mathbb{E}\{X(t + \tau)X(t)\} \cdot \mathbb{E}\{\cos(2\pi f_c(t + \tau) + \Psi) \cos(2\pi f_c t + \Psi)\} \\ &\quad + \mathbb{E}\{X(t + \tau)Y(t)\} \cdot \mathbb{E}\{\cos(2\pi f_c(t + \tau) + \Psi) \sin(2\pi f_c t + \Psi)\} \\ &\quad + \mathbb{E}\{Y(t + \tau)X(t)\} \cdot \mathbb{E}\{\sin(2\pi f_c(t + \tau) + \Psi) \cos(2\pi f_c t + \Psi)\} \\ &\quad + \mathbb{E}\{Y(t + \tau)Y(t)\} \cdot \mathbb{E}\{\sin(2\pi f_c(t + \tau) + \Psi) \sin(2\pi f_c t + \Psi)\} \end{aligned}$$

Let us solve or identify each of the involved expectations separately. We start by identifying those four:

$$\begin{aligned} \mathbb{E}\{X(t + \tau)X(t)\} &= r_X(\tau), \\ \mathbb{E}\{X(t + \tau)Y(t)\} &= r_{X,Y}(t + \tau, t), \\ \mathbb{E}\{Y(t + \tau)X(t)\} &= r_{Y,X}(t + \tau, t), \\ \mathbb{E}\{Y(t + \tau)Y(t)\} &= r_Y(\tau). \end{aligned}$$

Then we solve the remaining four, containing trigonometric functions:

$$\begin{aligned} \mathbb{E}\{\cos(2\pi f_c(t + \tau) + \Psi) \cos(2\pi f_c t + \Psi)\} &= \\ &= \frac{1}{2} \mathbb{E}\{\cos(2\pi f_c(2t + \tau) + 2\Psi) + \cos(2\pi f_c \tau)\} \\ &= \frac{1}{2} \cos(2\pi f_c \tau), \\ \mathbb{E}\{\cos(2\pi f_c(t + \tau) + \Psi) \sin(2\pi f_c t + \Psi)\} &= \\ &= \frac{1}{2} \mathbb{E}\{\sin(2\pi f_c(2t + \tau) + 2\Psi) - \sin(2\pi f_c \tau)\} \\ &= -\frac{1}{2} \sin(2\pi f_c \tau), \\ \mathbb{E}\{\sin(2\pi f_c(t + \tau) + \Psi) \cos(2\pi f_c t + \Psi)\} &= \\ &= \frac{1}{2} \mathbb{E}\{\sin(2\pi f_c(2t + \tau) + 2\Psi) + \sin(2\pi f_c \tau)\} \\ &= \frac{1}{2} \sin(2\pi f_c \tau), \\ \mathbb{E}\{\sin(2\pi f_c(t + \tau) + \Psi) \sin(2\pi f_c t + \Psi)\} &= \\ &= \frac{1}{2} \mathbb{E}\{-\cos(2\pi f_c(2t + \tau) + 2\Psi) + \cos(2\pi f_c \tau)\} \\ &= \frac{1}{2} \cos(2\pi f_c \tau). \end{aligned}$$

In all four cases above, the expectations of the sines and cosines with  $2\Psi$  in their arguments result in zero, since those become scaled integrals of two full periods of a sine. Totally, we have the ACF

$$\begin{aligned} r_Z(t + \tau, t) &= \\ &= \frac{1}{2} r_X(\tau) \cdot \cos(2\pi f_c \tau) - \frac{1}{2} r_{X,Y}(t + \tau, t) \cdot \sin(2\pi f_c \tau) \\ &\quad + \frac{1}{2} r_{Y,X}(t + \tau, t) \cdot \sin(2\pi f_c \tau) + \frac{1}{2} r_Y(\tau) \cdot \cos(2\pi f_c \tau) \\ &= \frac{1}{2} (r_X(\tau) + r_Y(\tau)) \cdot \cos(2\pi f_c \tau) \\ &\quad + \frac{1}{2} (r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t)) \cdot \sin(2\pi f_c \tau). \end{aligned}$$

We notice that  $r_Z(t + \tau, t)$  does not depend on  $t$  if

$$r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t)$$

does not depend on  $t$ . That is therefore the criterion that has to hold.

- b. A simple explicit example where  $X(t)$  and  $Y(t)$  are dependent, and where  $Z(t)$  is WSS, is if the two processes are the same, i.e. if we have  $X(t) = Y(t)$ , and we have

$$\begin{aligned} Z(t) &= X(t)(\cos(2\pi f_c t + \Psi) + \sin(2\pi f_c t + \Psi)) \\ &= \sqrt{2}X(t) \cos(2\pi f_c t + \Psi - \pi/4), \end{aligned}$$

which is ordinary AM. Then we have

$$r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t) = r_X(\tau) - r_X(\tau) = 0,$$

and our criterion from **a** is fulfilled.

A solution that does not use the result from **a** could be to observe that the additional phase-shift  $-\pi/4$  does not change anything significant. The normal expression for AM holds, given on Page 14 in T&F. That expression does not depend on  $t$ . The mean is zero in a similar way as above in **a**.

**Note:** There do indeed exist dependent processes  $X(t)$  and  $Y(t)$  such that

$$r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t)$$

depends on  $t$ . One such example is  $Y(t) = X(t) \cos(2\pi f_1 t)$ . We can also observe that if  $X(t)$  and  $Y(t)$  are jointly WSS, then both terms in

$$r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t)$$

are independent of  $t$ , resulting in  $Z(t)$  being WSS. Finally, if  $X(t)$  and  $Y(t)$  are independent processes, then we have

$$r_{Y,X}(t + \tau, t) = r_{X,Y}(t + \tau, t) = m_X m_Y.$$

That results in

$$r_{Y,X}(t + \tau, t) - r_{X,Y}(t + \tau, t) = 0.$$

#### 4

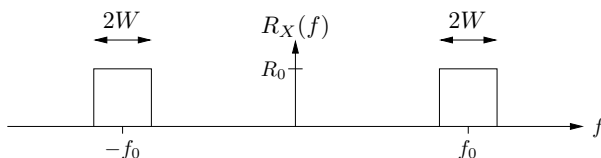
For the squarer we have

$$r_Y(\tau) = r_X^2(0) + 2r_X^2(\tau)$$

since  $X(t)$  is Gaussian with mean 0 (T&F, p. 15). This gives us

$$R_Y(f) = r_X^2(0)\delta(f) + 2(R_X * R_X)(f)$$

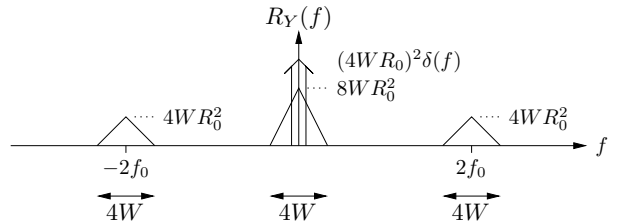
The PSD  $R_X(f)$  graphically:



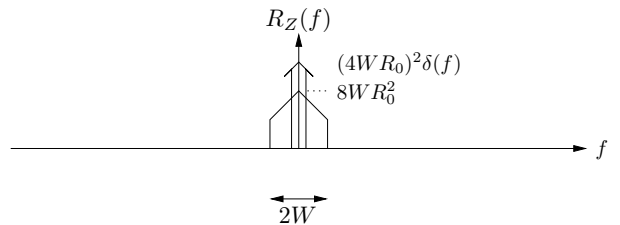
We have

$$r_X(0) = \int_{-\infty}^{\infty} R_X(f) df = 4WR_0.$$

The PSD  $R_Y(f)$  graphically:



After LP-filtering, we have the following PSD:



Finally, we integrate and get the power

$$\begin{aligned} P_Z &= E\{Z^2(t)\} = \int_{-\infty}^{\infty} R_Z(f) df \\ &= 16W^2 R_0^2 + 2W \cdot 4WR_0^2 + \frac{1}{2}2W \cdot 4WR_0^2 \\ &= 28W^2 R_0^2. \end{aligned}$$

#### 5

We are given a WSS time-discrete process  $X[n]$ , and the related process

$$Y[n] = \begin{cases} X[n+1], & n \text{ even,} \\ X[n-1], & n \text{ odd.} \end{cases}$$

- a. We want to express  $r_Y[n+k, n]$  in terms of  $r_X[k]$ . We have four cases, depending on if  $k$  and  $n$  are even or odd.

For the case where both  $k$  and  $n$  are even, we have

$$\begin{aligned} r_Y[n+k, n] &= E\{Y[n+k]Y[n]\} = \\ &= E\{X[n+k+1]X[n+1]\} = r_X[k]. \end{aligned}$$

For the case where  $k$  is even and  $n$  is odd, we have

$$\begin{aligned} r_Y[n+k, n] &= \mathbb{E}\{Y[n+k]Y[n]\} = \\ &= \mathbb{E}\{X[n+k-1]X[n-1]\} = r_X[k]. \end{aligned}$$

For the case where  $k$  is odd and  $n$  is even, we have

$$\begin{aligned} r_Y[n+k, n] &= \mathbb{E}\{Y[n+k]Y[n]\} = \\ &= \mathbb{E}\{X[n+k-1]X[n+1]\} = r_X[k-2]. \end{aligned}$$

For the case where both  $k$  and  $n$  are odd, we have

$$\begin{aligned} r_Y[n+k, n] &= \mathbb{E}\{Y[n+k]Y[n]\} = \\ &= \mathbb{E}\{X[n+k+1]X[n-1]\} = r_X[k+2]. \end{aligned}$$

- b.** First the mean: The mean  $m_X$  is constant since  $X[n]$  is WSS. Obviously,  $m_Y = m_X$ , since reordering the samples means reordering the mean, and  $m_X$  is constant.

Then the ACF: According to part **a**, for even  $k$  there is no dependence on  $n$ , but for odd  $k$  there is in general a dependence on  $n$ . Thus, in general  $Y[n]$  is not WSS. To remove the dependence on  $n$ , we must demand that

$$r_X[k-2] = r_X[k+2]$$

holds for all odd  $k$ .

## 6

We have a circular, WSS, complex process  $X(t)$ , and the related process  $Y(t) = e^{j\phi}X(t)$  for a fixed real-valued  $\phi$ .

- a.** We want to show that  $X(t)$  and  $Y(t)$  have the same PSD, which is equivalent to showing that  $X(t)$  and  $Y(t)$  have the same ACF, since the PSD of a process is the Fourier transform of the ACF of the same process. The ACF of the process  $Y(t)$  is given by

$$\begin{aligned} r_Y(\tau) &= \mathbb{E}\{Y(t+\tau)Y^*(t)\} \\ &= \mathbb{E}\{e^{j\phi}X(t+\tau)e^{-j\phi}X^*(t)\} \\ &= \mathbb{E}\{X(t+\tau)X^*(t)\} \\ &= r_X(\tau). \end{aligned}$$

So, they do in fact have the same ACF, and thus also the same PSD.

- b.** Let  $X_I(t)$  and  $X_Q(t)$  be the real and imaginary parts, respectively, of the complex signal  $X(t)$ , i.e. we have

$$X(t) = X_I(t) + jX_Q(t).$$

$X(t)$  is WSS and circular. Thus, we have

$$\begin{aligned} r_{X_I}(\tau) &= r_{X_Q}(\tau), \\ r_{X_I, X_Q}(\tau) &= -r_{X_Q, X_I}(\tau). \end{aligned}$$

According to the task formulation, we also have

$$\begin{aligned} Y(t) &= e^{j\phi}X(t) \\ &= (\cos(\phi) + j\sin(\phi))(X_I(t) + jX_Q(t)). \end{aligned}$$

Similarly, let  $Y_I(t)$  and  $Y_Q(t)$  be the real and imaginary part, respectively, of  $Y(t)$ . Then we have

$$\begin{aligned} Y_I(t) &= \text{Re}\{Y(t)\} \\ &= \cos(\phi)X_I(t) - \sin(\phi)X_Q(t), \\ Y_Q(t) &= \text{Im}\{Y(t)\} \\ &= \cos(\phi)X_Q(t) + \sin(\phi)X_I(t). \end{aligned}$$

Our task is now to check if

$$\begin{aligned} r_{Y_I}(\tau) &= r_{Y_Q}(\tau), \\ r_{Y_I, Y_Q}(\tau) &= -r_{Y_Q, Y_I}(\tau), \end{aligned}$$

hold for all real  $\phi$ .

We have

$$\begin{aligned} r_{Y_I}(\tau) &= \\ &= \mathbb{E}\left\{(\cos(\phi)X_I(t+\tau) - \sin(\phi)X_Q(t+\tau)) \cdot (\cos(\phi)X_I(t) - \sin(\phi)X_Q(t))\right\} \\ &= \cos^2(\phi)r_{X_I}(\tau) + \sin^2(\phi)r_{X_Q}(\tau) \\ &\quad - \cos(\phi)\sin(\phi)(r_{X_I, X_Q}(\tau) + r_{X_Q, X_I}(\tau)) \\ &= (\cos^2(\phi) + \sin^2(\phi))r_{X_I}(\tau) \\ &\quad - \cos(\phi)\sin(\phi)(r_{X_I, X_Q}(\tau) - r_{X_I, X_Q}(\tau)) \\ &= r_{X_I}(\tau), \end{aligned}$$

where we have used the assumption that  $X(t)$  is circular in the second last equality. This holds regardless of  $\phi$ . Therefore, we also have

$$r_{Y_Q}(\tau) = r_{X_I}(\tau).$$

We have thus showed the equality

$$r_{Y_I}(\tau) = r_{Y_Q}(\tau).$$

Then we have

$$\begin{aligned}
 r_{Y_I, Y_Q}(\tau) &= \\
 &= \mathbb{E} \left\{ \left( \cos(\phi) X_I(t + \tau) - \sin(\phi) X_Q(t + \tau) \right) \cdot \right. \\
 &\quad \left. \cdot \left( \cos(\phi) X_Q(t) + \sin(\phi) X_I(t) \right) \right\} \\
 &= \cos^2(\phi) r_{X_I, X_Q}(\tau) - \sin^2(\phi) r_{X_Q, X_I}(\tau) \\
 &\quad + \cos(\phi) \sin(\phi) (r_{X_I}(\tau) - r_{X_Q}(\tau)) \\
 &= (\cos^2(\phi) + \sin^2(\phi)) r_{X_I, X_Q}(\tau) \\
 &\quad + \cos(\phi) \sin(\phi) (r_{X_I}(\tau) - r_{X_I}(\tau)) \\
 &= r_{X_I, X_Q}(\tau),
 \end{aligned}$$

where we again have use the assumption that  $X(t)$  is circular in the second last equality. Similarly, we have

$$r_{Y_Q, Y_I}(\tau) = -r_{X_I, X_Q}(\tau).$$

We have thus showed the equality

$$r_{Y_I, Y_Q}(\tau) = -r_{Y_Q, Y_I}(\tau).$$

To conclude,  $Y(t)$  is circular for all  $\phi$ .