TSKS01 Digital Communication Lecture 4

Digital Modulation – Basis Functions and Basic Signal Detection

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### Last Time – Digital Modulation

Signals:

AWGN:

 $s_i(t) = \sum_{j=0}^{N-1} s_{i,j} \phi_j(t), \qquad i = 0, 1, \dots, M-1,$  $0 \leq t < T$ **ON** basis  $W(t) = \sum_{j=0}^{N-1} W_j \phi_j(t) + W'(t)$ Irrelevant  $W_i = (W, \phi_i)$ 

Gaussian with mean 0.

Received: 
$$X(t) = s_i(t) + W(t) = \sum_{j=0}^{N-1} X_j \phi_j(t) + W'(t)$$
  $X_j = (X, \phi_j)$   
Gaussian with mean  $s_{i,j}$ .

Vectors:

$$X = \overline{s}_{i} + W$$

$$X = \overline{s}_{i} + W$$

$$X_{0}$$

$$S_{i,0}$$

$$S_{i,0}$$

$$W_{0}$$

$$W_{0}$$

$$W_{0}$$

$$W_{N-1}$$

Orthogonal noise components are statistically independent.  $\sigma_{W_i}^2 = \sigma_{X_i}^2 = R_W(f) = N_0/2$ 





### **Indicator Function**

**Definition:** The *indicator function*  $I_A(t)$  of the set A is given by

$$I_A(t) = \begin{cases} 1, & t \in A \\ 0, & \text{elsewhere} \end{cases}$$

#### Examples:





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# Example of Basis Functions (N = 1)

Time-limited baseband signal

$$\tilde{\phi}_0(t) = \sqrt{\frac{1}{T}} I_{\{0 \le t < T\}}(t)$$

• Time-limited passband signal (carrier frequency  $f_c$ )

$$\phi_0(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_c t) I_{\{0 \le t < T\}}(t)$$

• 
$$\|\phi_0\|^2 = \frac{2}{T} \int_0^T \cos^2(2\pi f_c t) dt = 1 - \frac{2}{T} \int_0^T \cos(4\pi f_c t) dt$$

Equal to one if  $4f_cT$  is an integer



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# Example of Basis Functions (N = 2)

• Time-limited passband signal (carrier frequency  $f_c$ )

$$\phi_0(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_c t) I_{\{0 \le t < T\}}(t)$$

$$\phi_1(t) = -\sqrt{\frac{2}{T}} \sin(2\pi f_c t) I_{\{0 \le t < T\}}(t)$$

• When are these functions orthogonal?

$$\int_{-\infty}^{\infty} \phi_0(t)\phi_1(t)dt = \dots = -\frac{1}{T}\int_0^T \sin(4\pi f_c t) dt$$

#### Equal to zero if $2f_cT$ is an integer



# Energy Spectra: $|\Phi_0(f)|$ and $|\Phi_1(f)|$



# Example of Basis Functions (N > 2)

- How to construct more than two basis functions?
  - One can show that  $\cos(2\pi f_0 t) I_{\{0 \le t < T\}}(t)$  and  $\cos(2\pi f_k t) I_{\{0 \le t < T\}}(t)$ are orthogonal if  $(f_0 - f_k)T$  is an integer
- Proposal (N/2 is an integer):

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$$f_{k} = f_{0} + \frac{k}{T} \quad \text{for } k = 0, 1, \dots, \frac{N}{2} - 1$$
$$\phi_{2k}(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_{k}t) I_{\{0 \le t < T\}}(t)$$
$$\phi_{2k+1}(t) = -\sqrt{\frac{2}{T}} \sin(2\pi f_{k}t) I_{\{0 \le t < T\}}(t)$$

N/2 pairs of cosine and sine

$$\phi_{2k+1}(t) = -\sqrt{\frac{2}{T}}\sin(2\pi f_k t) I_{\{0 \le t < T\}}(t)$$





# Energy Spectra: $|\Phi_n(f)|$ n = 0, ... N - 1





# Single and Multi Carrier Modulation 1(2)

- Given total bandwidth *B* 
  - Approximate bandwidth: count only the main lobe
- Single Carrier (N = 2)

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• 
$$B = \frac{2}{T} \quad \leftrightarrow \quad T = \frac{2}{B}$$

• Multi Carrier (N > 2, N/2 integer)

• 
$$B = \left(\frac{N}{2} + 1\right) \cdot \frac{1}{T} \qquad \leftrightarrow \qquad T = \left(\frac{N}{2} + 1\right) \cdot \frac{1}{B}$$

- Example: N = 1024: T is 256.5 times larger with multi carrier
  - Main lobe is 256.6 times smaller



# Single and Multi Carrier Modulation 2(2)

- Frequency response of channel
  - Changes with frequency
  - Approx. fixed over small interval



$$h(t) = \delta(t - \tau_1) + \delta(t - \tau_2) + \delta(t - \tau_3) + \delta(t - \tau_4)$$

#### **Multi Carrier**

Select *N* large enough: Make H(f) approximately constant over the main lobe 2/T

#### Can ignore channel:

This is what we will do right now

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# **Receiving a Modulated Signal**



$$X_j \triangleq (X, \phi_j)$$

#### Next topic: The demodulator and vector detector



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### Demodulation



Projections: $s_{i,j} = (s_i, \phi_j) = \int_0^T s_i(t) \phi_j(t) dt$ Signals are<br/>projected on<br/>basis functionsNoise is<br/>projected on<br/>basis functions $W_j = (W, \phi_j) = \int_0^T W(t) \phi_j(t) dt$ Signals are<br/>projected on<br/>basis functions $X_j = (X, \phi_j) = \int_0^T X(t) \phi_j(t) dt$ Do this! $X_j = s_{i,j} + W_j$  $j \in \{0, 1, \dots, N-1\}.$ 



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#### **Correlation Receiver**



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13

# **Matched Filters**

#### **Definition:**

A filter with impulse response  $h_j(t) = \phi_j(T - t)$  is matched to  $\phi_j(t)$ 

Example:



Usage  $(\phi_j * h_j)(t)$ :



Orthogonal signal  $\phi_i(t)$ :

Then  $(\phi_i * h_j)(t)$ :

Zero at 
$$t = T$$

 $(\phi_i(t),\phi_j(t)) = 0$ 

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### **Demodulation Using Matched Filters**



Filter:  $h_j(t) \triangleq \phi_j(T-t)$  Matched to  $\phi_j(t)$ 

Output:  $Y_j(t) = (X * h_j)(t)$   $\checkmark$  Do this!  $= \int_{-\infty}^{\infty} X(\tau) h_j(t-\tau) d\tau = \int_{t-T}^{t} X(\tau) \phi_j(T-t+\tau) d\tau$ 

Sample at t = T:  $Y_j(T) = \int_0^T X(\tau) \phi_j(\tau) d\tau = (X, \phi_j) = X_j$ And this!





### **Matched Filter Receiver**



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16

### **The Vector Detector**



The task of the vector detector:

Observe  $\bar{x}$  and output  $\hat{a}$  according to a well chosen decision rule, designed to minimize the error probability.

What do we know?

All entities are realizations of stochastic variables.

Use statistical descriptions of those stochastic variables!





#### **Vector Detection**



Received vector:  $\overline{x}$ 

Goal: Minimize the error probability



#### **Equivalent decision rule:**

Set  $\hat{a} = a_i$  if  $\Pr\{A = a_k | \overline{X} = \overline{x}\}$  is maximized for k = i.



#### Detection







# Maximum Likelihood (ML) Detection

Assumption:  $\Pr\{A = a_i\} = \frac{1}{M}$  for i = 0, 1, ..., M - 1

**ML decision rule:** Set  $\hat{a} = a_i$  if  $f_{\bar{X}|A}(\bar{x}|a_k)$  is maximized for k = i.

Independent variables:

$$f_{\overline{X}|A}(\overline{x} \mid a_k) = \prod_{j=0}^{N-1} f_{X_j|A}(x_j \mid a_k) = \prod_{j=0}^{N-1} \frac{1}{\sqrt{\pi N_0}} \cdot e^{-(x_j - s_{k,j})^2/N_0} = (\pi N_0)^{-N/2} \cdot e^{-\frac{1}{N_0} \sum_{j=0}^{N-1} (x_j - s_{k,j})^2}$$

Natural logarithm (strictly increasing function):  $\ln\left(f_{\bar{X}|A}(\bar{x} \mid a_k)\right) = -\frac{N}{2}\ln(\pi N_0) - \frac{1}{N_0}\sum_{j=0}^{N-1}(x_j - s_{k,j})^2 = -\frac{N}{2}\ln(\pi N_0) + \frac{1}{N_0}d^2(\bar{x}, \bar{s}_k)$ 

**Equivalent ML rule:** Set  $\hat{a} = a_i$  if  $d(\bar{x}, \bar{s}_k)$  is minimized for k = i.





# **ML Decision Regions**



Detect  $\overline{x}$  as being the nearest signal.

Result:

Decision regions consist of all points closest to a signal point.

Notation:

 $B_i$  is the decision region of the signal vector  $\overline{s}_i$ . Thus also of the signal  $s_i(t)$ and of the message  $a_i$ .

Borders are orthogonal to straight lines between signals: In 2 dimensions: Lines. In 3 dimensions: Planes. Higher dim: Hyperplanes. Borders cut the lines mid-way.





### **Error Probability**

Symbol error probability:

$$P_{e} = \Pr\left\{\hat{A} \neq A\right\} = \sum_{i=0}^{M-1} \Pr\left\{A = a_{i}\right\} \cdot \Pr\left\{\hat{A} \neq a_{i} \mid A = a_{i}\right\}$$
$$= \sum_{i=0}^{M-1} \Pr\left\{A = a_{i}\right\} \cdot \Pr\left\{\overline{X} \notin B_{i} \mid A = a_{i}\right\}$$

ML detection:  $Pr\{A = a_i\} = \frac{1}{M}$  for i = 0, 1, ..., M - 1:

$$P_{e} = \frac{1}{M} \sum_{i=0}^{M-1} \Pr\{\overline{X} \notin B_{i} \mid A = a_{i}\} = \frac{1}{M} \sum_{i=0}^{M-1} \int_{\overline{x} \notin B_{i}} \cdots \int_{\overline{X}|A} (\overline{x} \mid a_{i}) dx_{0} \cdots dx_{N-1}$$

This is generally hard to calculate!



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# Special Case: Two signals in N = 1 Dimension



$$\Pr\left\{\overline{X} \notin B_0 \mid A = a_0\right\} = \Pr\left\{\overline{X} \in B_1 \mid A = a_0\right\} = \Pr\left\{X_0 > \frac{s_{0,0} + s_{1,0}}{2} \mid A = a_0\right\}$$
$$= \Pr\left\{W_0 > \frac{s_{0,0} + s_{1,0}}{2} - s_{0,0} \mid A = a_0\right\} = \Pr\left\{W_0 > \frac{s_{1,0} - s_{0,0}}{2}\right\} \qquad \text{This value}$$

 $= \Pr\left\{ W_0 > \frac{d(s_0, s_1)}{2} \right\} = Q\left(\frac{d(s_0, s_1)/2}{\sqrt{N_0/2}}\right) = Q\left(\frac{d(s_0, s_1)}{\sqrt{2N_0}}\right)$ 

This works in all directions.



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Similarly for  $\Pr\{\overline{X} \notin B_1 \mid A = a_1\}$ .  $\Rightarrow P_e = Q(\cdots)$ 





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