

TSDT14 Signal Theory

Lecture 10

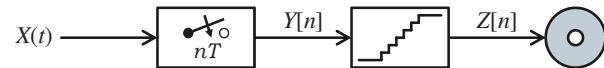
Reconstruction in CD Players

Exam Problems

Mikael Olofsson
Department of EE (ISY)
Div. of Communication Systems



CDs at Recording 1(2)



Band-limited input: $R_X(f) \approx 0, |f| \geq B = 20 \text{ kHz}$

Sampling frequency: $f_s = 44.1 \text{ kHz}$

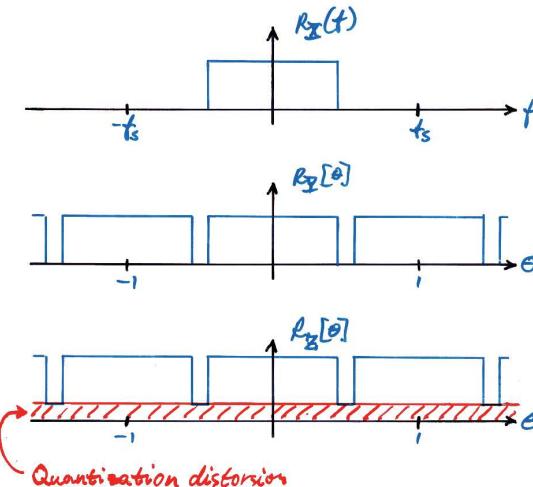
Uniform quantization: 16 bits $\Rightarrow N = 2^{16}$ steps

Saturation level: A $\Delta^2 = \frac{A^2}{12} = \frac{A^2}{2^{32} \cdot 3}$

Quantization step height: Δ

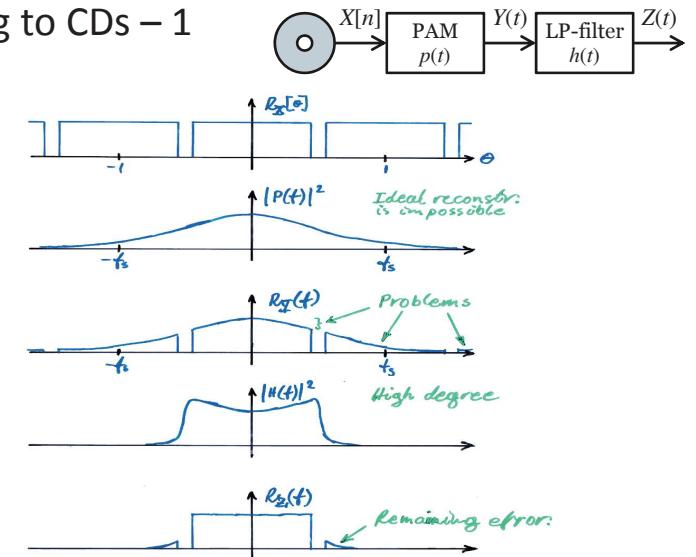
Signal-to-Distortion Ratio: $\text{SDR}_{\max} = 10 \log_{10}(2^{32}) \approx 96 \text{ dB}$

CDs at Recording 2(2)



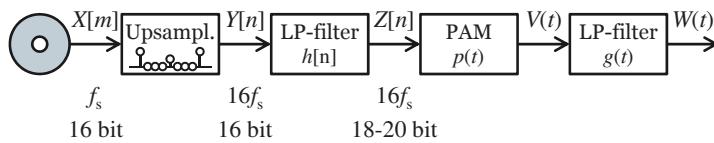
Listening to CDs – 1

Direct PAM



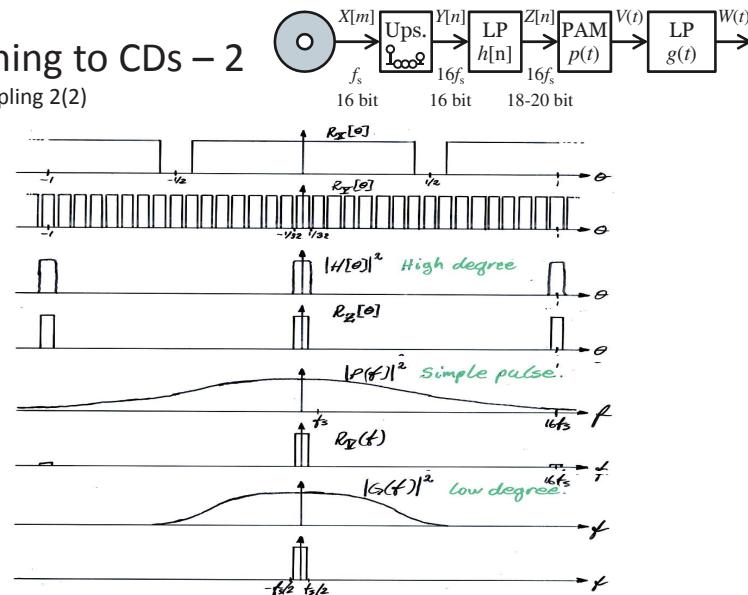
Listening to CDs – 2

Oversampling 1(2)



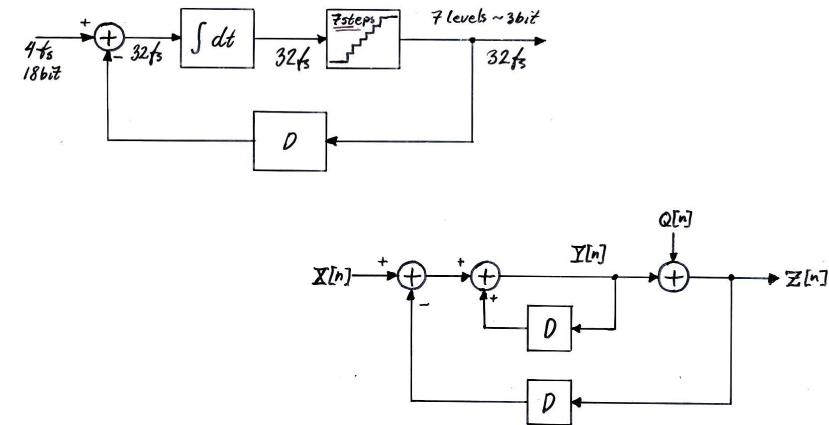
Listening to CDs – 2

Oversampling 2(2)



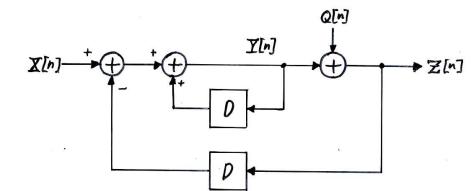
Listening to CDs – 3

Noise Shaping 1(4) – Principle of First-Order Noise Shaper



Listening to CDs – 3

Noise Shaping 2(4) – Analysis 1



If no $Q[n]$:

$$Z[n] = Y[n] = X[n] + Y[n-1] - Z[n-1] = X[n]$$

Error: $S[n] = Z[n] - X[n]$
 $\text{Fig} \Rightarrow \left. \begin{aligned} Y[n] &= X[n] + Y[n-1] - Z[n-1] \\ Z[n] &= Y[n] + Q[n] \end{aligned} \right\} \Rightarrow$

$$\Rightarrow S[n] = (X[n] + Y[n-1] - Z[n-1]) + Q[n] - X[n] \\ = Q[n] - Q[n-1]$$

Interpretation:
The quantization noise is filtered.

$$h[n] = \delta[n] - \delta[n-1]$$

$$H[\theta] = 1 - e^{-j2\pi\theta} \\ = 2j e^{-j\pi\theta} \sin(\pi\theta)$$

Listening to CDs – 3

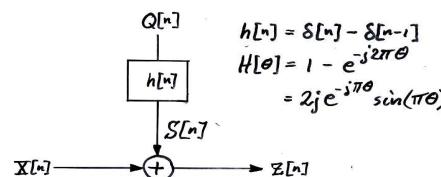
Noise Shaping 3(4) – Analysis 2

Quantization error: $Q[n]$:

$$\frac{\Delta^2}{12} = \frac{A^2}{\pi^2} \cdot \frac{1}{3} = \frac{A^2}{147} \Rightarrow r_Q[k] = \frac{A^2}{147} \delta[k], R_Q[\theta] = \frac{A^2}{147}$$

Error: $S[n]$:

$$R_S[\theta] = |H[\theta]|^2 R_Q[\theta] = \frac{4A^2}{147} \sin^2(\pi\theta)$$



Error power in audio range ($\sin x \approx x$ for small x)

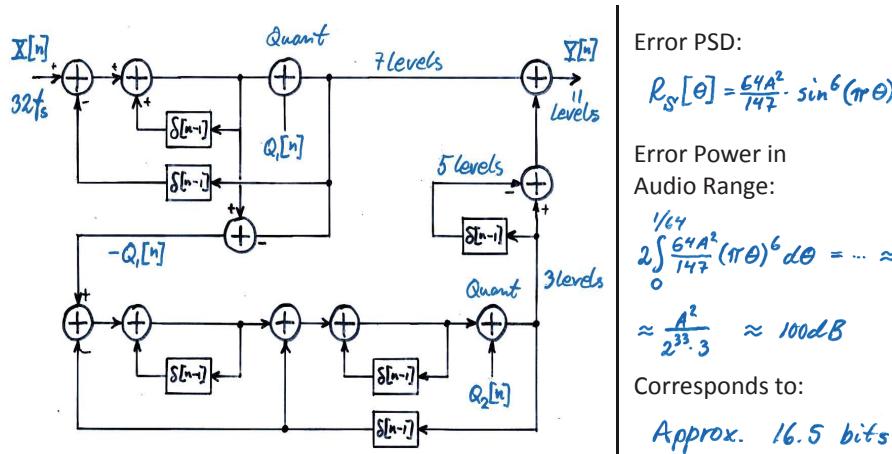
$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} R_S[\theta] d\theta = 2 \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{4A^2}{147} \sin^2(\pi\theta) d\theta \approx \frac{A^2}{20} \int_0^{\frac{\pi}{2}} (\pi\theta)^2 d\theta$$

$$\approx \frac{A^2}{2} \int_0^{\frac{\pi}{2}} \theta^2 d\theta = \frac{A^2}{2} \left[\frac{\theta^3}{3} \right]_0^{\frac{\pi}{2}} = \frac{A^2}{2} \cdot \frac{\pi^3}{24} \approx 57dB$$

Approx. 9.5 bits

Listening to CDs – 3

Noise Shaping 4(4) – Implementation of Third-Order Noise Shaper

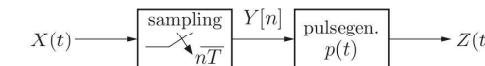


2010-08-28 – Problem 4

The time-continuous process $X(t)$ is bandlimited white noise with mean $m_X = 0$ and PSD

$$R_X(f) = \begin{cases} 1, & |f| \leq W, \\ 0, & \text{elsewhere.} \end{cases}$$

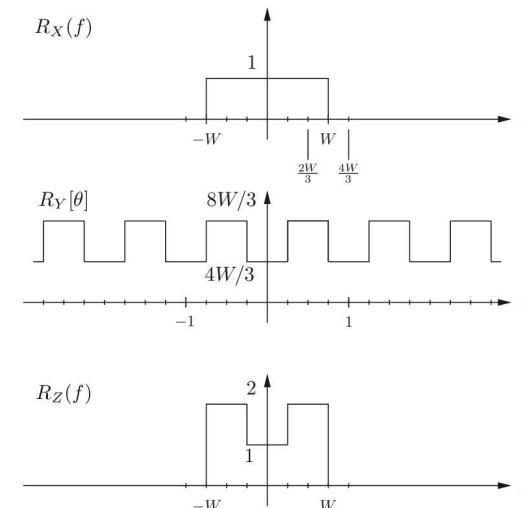
The signal $X(t)$ is sampled and pulse-amplitude-modulated according to the figure below.



The sampling frequency is $f_s = \frac{1}{T} = \frac{4W}{3}$ and the pulse shape of the PAM is $p(t) = \frac{3 \sin(2\pi Wt)}{4\pi Wt}$.

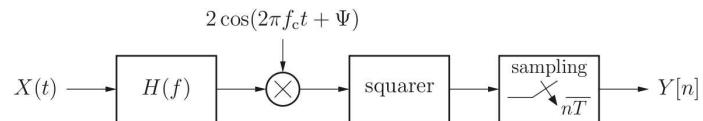
- a) Determine and draw the PSDs $R_Y[\theta]$ and $R_Z(f)$. (3 p)
- b) Determine the reconstruction error $\varepsilon^2 = E\{(Z(t) - X(t))^2\}$. (2 p)

2010-08-28 – Problem 4 – PSDs



2009-10-23 – Problem 3

The input $X(t)$ to the system below is a strictly stationary white process with PSD R_0 , and the stochastic variable Ψ is as usual uniformly distributed on $[0, 2\pi)$ and independent of $X(t)$. The input is Gaussian with mean 0.



The initial filter has frequency response

$$H(f) = \begin{cases} 2, & |f| < f_0, \\ 0, & \text{elsewhere.} \end{cases}$$

Note: This is one of the tasks from Tutorial 8.

The carrier frequency is $f_c = 2f_0$, while the sampling frequency is $f_s = 3f_0$.

Calculate the power P_Y of the output $Y[n]$. (5 p)